# On the continuity property of $L_{p}$ balls and an application ${ }^{\text {NT }}$ 

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#### Abstract

In this paper continuity properties of the set-valued map $p \rightarrow B_{p}\left(\mu_{0}\right), p \in(1,+\infty)$, are considered where $B_{p}\left(\mu_{0}\right)$ is the closed ball of the space $L_{p}\left(\left[t_{0}, \theta\right] ; R^{m}\right)$ centered at the origin with radius $\mu_{0}$. It is proved that the set-valued map $p \rightarrow B_{p}\left(\mu_{0}\right), p \in(1,+\infty)$, is continuous. Applying obtained results, the attainable set of the nonlinear control system with integral constraint on the control is studied. The admissible control functions are chosen from $B_{p}\left(\mu_{0}\right)$. It is shown that the attainable set of the system is continuous with respect to $p$. © 2007 Elsevier Inc. All rights reserved.


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## 1. Introduction

Let $\|\cdot\|$ be Euclidean norm in $R^{m},\|u(\cdot)\|_{p}(1 \leqslant p<+\infty)$ be a norm in $L_{p}\left(\left[t_{0}, \theta\right], R^{m}\right)$, where $L_{p}\left(\left[t_{0}, \theta\right], R^{m}\right)$ denotes the space of measurable functions $u(\cdot):\left[t_{0}, \theta\right] \rightarrow R^{m}$ with bounded $\|u(\cdot)\|_{p}$ norm and

$$
\|u(\cdot)\|_{p}=\left(\int_{t_{0}}^{\theta}\|u(t)\|^{p} d t\right)^{\frac{1}{p}}
$$

[^0]For $p \geqslant 1$ and $\mu_{0}>0$ we set

$$
\begin{equation*}
B_{p}\left(\mu_{0}\right)=\left\{u(\cdot) \in L_{p}\left(\left[t_{0}, \theta\right], R^{m}\right):\|u(\cdot)\|_{p} \leqslant \mu_{0}\right\} \tag{1.1}
\end{equation*}
$$

It is obvious that $B_{p}\left(\mu_{0}\right)$ is the closed ball centered at the origin with radius $\mu_{0}$ in $L_{p}\left(\left[t_{0}, \theta\right], R^{m}\right)$.

The Hausdorff distance between the sets $A \subset R^{m}$ and $E \subset R^{m}$ is denoted by $h(A, E)$ and is defined as

$$
h(A, E)=\max \left\{\sup _{x \in A} d(x, E), \sup _{y \in E} d(y, A)\right\}
$$

where $d(x, E)=\inf \{\|x-y\|: y \in E\}$.
The Hausdorff distance between the sets $U \subset L_{p_{1}}\left(\left[t_{0}, \theta\right], R^{m}\right)$ and $V \subset L_{p_{2}}\left(\left[t_{0}, \theta\right], R^{m}\right)$ is denoted by $h_{1}(U, V)$ and is defined as

$$
h_{1}(U, V)=\max \left\{\sup _{x(\cdot) \in V} d_{1}(x(\cdot), U), \sup _{y(\cdot) \in U} d_{1}(y(\cdot), V)\right\}
$$

where $d_{1}(x(\cdot), U)=\inf \left\{\|x(\cdot)-y(\cdot)\|_{1}: y(\cdot) \in U\right\}, p_{1} \in[1, \infty), p_{2} \in[1, \infty)$.
For $\Omega \subset R^{n}$ we denote by $\mu(\Omega)$ the Lebesgue measure of the set $\Omega$.
The need to evaluate the distance between the sets arises in various problems of theory and applications (see, e.g., $[1,2,4-6,8-10,13]$ and references therein).

In this paper, the Hausdorff distance between the sets $B_{p}\left(\mu_{0}\right)$ and $B_{p_{*}}\left(\mu_{0}\right)$ is studied where $p>1$ and $p_{*}>1$. In Section 2 we prove that $h_{1}\left(B_{p}\left(\mu_{0}\right), B_{p_{*}}\left(\mu_{0}\right)\right) \rightarrow 0$ as $p \rightarrow p_{*}-0$ (Proposition 2.5). In Section 3 it is shown that $h_{1}\left(B_{p}\left(\mu_{0}\right), B_{p_{*}}\left(\mu_{0}\right)\right) \rightarrow 0$ as $p \rightarrow p_{*}+0$ (Proposition 3.5). As a corollary of Propositions 2.5 and 3.5 , Theorem 3.6 concludes that $h_{1}\left(B_{p}\left(\mu_{0}\right), B_{p_{*}}\left(\mu_{0}\right)\right) \rightarrow 0$ as $p \rightarrow p_{*}$. In Section 4 we consider attainable sets of the nonlinear control system with integral constraints on control. $B_{p}\left(\mu_{0}\right)$ is chosen as the set of admissible control functions. As an application of Theorem 3.6, it is proved that the attainable set of the control system is continuous with respect to $p$ (Theorem 4.2).

Let $H \in(0, \infty)$. We set

$$
B_{p}^{H}\left(\mu_{0}\right)=\left\{u(\cdot) \in B_{p}\left(\mu_{0}\right):\|u(t)\| \leqslant H \text { for every } t \in\left[t_{0}, \theta\right]\right\} .
$$

The following proposition characterizes the Hausdorff distance between the sets $B_{p}\left(\mu_{0}\right)$ and $B_{p}^{H}\left(\mu_{0}\right)$.

Proposition 1.1. Let $p>1, H>0$. Then the inequality

$$
h_{1}\left(B_{p}\left(\mu_{0}\right), B_{p}^{H}\left(\mu_{0}\right)\right) \leqslant \frac{2 \mu_{0}^{p}}{H^{p-1}}
$$

holds.

Proof. Let us choose an arbitrary $u(\cdot) \in B_{p}\left(\mu_{0}\right)$ and define a function $u_{*}(\cdot):\left[t_{0}, \theta\right] \rightarrow R^{m}$, setting for $t \in\left[t_{0}, \theta\right]$

$$
u_{*}(t)= \begin{cases}u(t), & \|u(t)\| \leqslant H  \tag{1.2}\\ \frac{u(t)}{\|u(t)\|} H, & \|u(t)\|>H\end{cases}
$$

It is not difficult to verify that $u_{*}(\cdot) \in B_{p}^{H}\left(\mu_{0}\right)$. Let

$$
\Omega=\left\{\tau \in\left[t_{0}, \theta\right]:\|u(\tau)\|>H\right\}
$$

Then using Hölder and Minkowski inequalities, we have from (1.2) that

$$
\begin{equation*}
\left\|u(\cdot)-u_{*}(\cdot)\right\|_{1}=\int_{\Omega}\left\|u(t)-u_{*}(t)\right\| d t \leqslant 2 \mu_{0} \mu(\Omega)^{\frac{p-1}{p}} \tag{1.3}
\end{equation*}
$$

Since $u(\cdot) \in B_{p}\left(\mu_{0}\right)$ and $\|u(\tau)\|>H$ for every $\tau \in \Omega$, we obtain

$$
H^{p} \mu(\Omega) \leqslant \int_{\Omega}\|u(\tau)\|^{p} d \tau \leqslant \int_{t_{0}}^{\theta}\|u(\tau)\|^{p} d \tau \leqslant \mu_{0}^{p}
$$

and consequently

$$
\begin{equation*}
\mu(\Omega) \leqslant \frac{\mu_{0}^{p}}{H^{p}} \tag{1.4}
\end{equation*}
$$

Then it follows from (1.3) and (1.4)

$$
\left\|u(\cdot)-u_{*}(\cdot)\right\|_{1} \leqslant 2 \mu_{0}\left(\frac{\mu_{0}^{p}}{H^{p}}\right)^{\frac{p-1}{p}}=\frac{2 \mu_{0}^{p}}{H^{p-1}} .
$$

Since $u(\cdot) \in B_{p}\left(\mu_{0}\right)$ is arbitrarily chosen, we get the inequality

$$
\begin{equation*}
\sup _{u(\cdot) \in B_{p}\left(\mu_{0}\right)} d_{1}\left(u(\cdot), B_{p}^{H}\left(\mu_{0}\right)\right) \leqslant \frac{2 \mu_{0}^{p}}{H^{p-1}} . \tag{1.5}
\end{equation*}
$$

Since $B_{p}^{H}\left(\mu_{0}\right) \subset B_{p}\left(\mu_{0}\right)$ then (1.5) completes the proof of the proposition.
We obtain the following corollary from Proposition 1.1.

Corollary 1.2. Let $p_{*}>1$ and $\varepsilon>0$. Then there exists $H_{*}(\varepsilon)>2 \mu_{0}$ such that for all $H>H_{*}(\varepsilon)$ the inequality

$$
h_{1}\left(B_{p}\left(\mu_{0}\right), B_{p}^{H}\left(\mu_{0}\right)\right) \leqslant \varepsilon
$$

holds for any $p \in\left[\frac{p_{*}+1}{2}, 2 p_{*}\right]$.

## 2. Left evaluation of $\boldsymbol{B}_{\boldsymbol{p}}\left(\mu_{0}\right)$

In this section, we will evaluate the Hausdorff distance between the sets $B_{p}\left(\mu_{0}\right)$ and $B_{p_{*}}\left(\mu_{0}\right)$ as $p \rightarrow p_{*}-0$.

Let

$$
\begin{equation*}
\alpha_{0}=\min \left\{\frac{\mu_{0}}{2}, 1\right\} . \tag{2.1}
\end{equation*}
$$

Proposition 2.1. Let $p_{*}>1, \varepsilon \in\left(0, \alpha_{0}\right)$ and $H_{2}>H_{1}>2 \mu_{0}$. Then there exists $\delta_{1}=$ $\delta_{1}\left(\varepsilon, H_{1}, H_{2}\right) \in\left(0, \frac{p_{*}-1}{2}\right]$ such that the inclusion

$$
B_{p_{*}}^{H_{1}}\left(\mu_{0}\right) \subset B_{p}^{H_{2}}\left(\mu_{0}\right)+2\left(\theta-t_{0}\right) \varepsilon B_{1}(1)
$$

holds for all $p \in\left(p_{*}-\delta_{1}, p_{*}\right)$ where $\alpha_{0}>0$ is defined by (2.1) and $B_{1}(1)$ is defined by (1.1).
Proof. Let

$$
\delta_{1}\left(\varepsilon, H_{1}, H_{2}\right)=\min \left\{\beta_{1}\left(\varepsilon, H_{1}\right), \beta_{2}\left(\varepsilon, H_{1}\right), p_{*}-p_{1}\left(H_{1}, H_{2}\right)\right\}
$$

where

$$
\begin{aligned}
& p_{1}\left(H_{1}, H_{2}\right)=\max \left\{\frac{p_{*}+1}{2}, \frac{p_{*}}{1+\log _{\frac{H_{1}}{\mu_{0}}} \frac{H_{2}}{H_{1}}}\right\}, \\
& \beta_{1}\left(\varepsilon, H_{1}\right)=p_{*}\left(1-\frac{1}{1+\log _{\frac{H_{1}}{\mu_{0}}} \frac{H_{1}+\varepsilon}{H_{1}}}\right), \\
& \beta_{2}\left(\varepsilon, H_{1}\right)=p_{*}\left(1-\frac{1}{1+\log _{\frac{\varepsilon}{\mu_{0}}} \frac{H_{1}-\varepsilon}{H_{1}}}\right) .
\end{aligned}
$$

It is not difficult to verify that $\delta_{1}\left(\varepsilon, H_{1}, H_{2}\right) \in\left(0, \frac{p_{*}-1}{2}\right]$.
Let $u_{*}(\cdot) \in B_{p_{*}}^{H_{1}}\left(\mu_{0}\right)$ be arbitrarily chosen and $p \in\left(p_{*}-\delta_{1}\left(\varepsilon, H_{1}, H_{2}\right), p_{*}\right)$. We set

$$
\begin{equation*}
u_{p}(t)=u_{*}(t)\left\|u_{*}(t)\right\|^{\frac{p_{*}-p}{p}} \mu_{0} \frac{p-p_{*}}{p}, \quad t \in\left[t_{0}, \theta\right] . \tag{2.2}
\end{equation*}
$$

Since $u_{*}(\cdot) \in B_{p_{*}}^{H_{1}}\left(\mu_{0}\right)$ and $p \in\left(p_{*}-\delta_{1}\left(\varepsilon, H_{1}, H_{2}\right), p_{*}\right)$, it is possible to prove that $u_{p}(\cdot) \in$ $B_{p}^{H_{2}}\left(\mu_{0}\right)$.

Denote

$$
A(\varepsilon)=\left\{t \in\left[t_{0}, \theta\right]: 0 \leqslant\left\|u_{*}(t)\right\| \leqslant \varepsilon\right\}, \quad B(\varepsilon)=\left\{t \in\left[t_{0}, \theta\right]: \varepsilon<\left\|u_{*}(t)\right\| \leqslant H_{1}\right\} .
$$

Let $t \in A(\varepsilon)$. Then $0 \leqslant\left\|u_{*}(t)\right\| \leqslant \varepsilon$. Since $\varepsilon<\frac{\mu_{0}}{2}$ and $p<p_{*}$ then we obtain

$$
\begin{equation*}
\left\|u_{*}(t)\right\|\left|1-\left(\frac{\left\|u_{*}(t)\right\|}{\mu_{0}}\right)^{\frac{p_{*}-p}{p}}\right| \leqslant \varepsilon \tag{2.3}
\end{equation*}
$$

for every $t \in A(\varepsilon)$.
Let $t \in B(\varepsilon)$. Then $\varepsilon<\left\|u_{*}(t)\right\| \leqslant H_{1}$ and this gives

$$
\begin{equation*}
1-\left(\frac{H_{1}}{\mu_{0}}\right)^{\frac{p_{*}-p}{p}} \leqslant 1-\left(\frac{\left\|u_{*}(t)\right\|}{\mu_{0}}\right)^{\frac{p_{*}-p}{p}} \leqslant 1-\left(\frac{\varepsilon}{\mu_{0}}\right)^{\frac{p_{*}-p}{p}} . \tag{2.4}
\end{equation*}
$$

Since $p \in\left(p_{*}-\delta_{1}\left(\varepsilon, H_{1}, H_{2}\right), p_{*}\right)$, then we get from (2.4) that the inequality

$$
\left|1-\left(\frac{\left\|u_{*}(t)\right\|}{\mu_{0}}\right)^{\frac{p *-p}{p}}\right| \leqslant \frac{\varepsilon}{H_{1}}
$$

holds for every $t \in B(\varepsilon)$ and consequently

$$
\begin{equation*}
\left\|u_{*}(t)\right\|\left|1-\left(\frac{\left\|u_{*}(t)\right\|}{\mu_{0}}\right)^{\frac{p_{*}-p}{p}}\right| \leqslant \varepsilon . \tag{2.5}
\end{equation*}
$$

Finally, it follows from (2.3) and (2.5) that

$$
\begin{equation*}
\left\|u_{p}(\cdot)-u_{*}(\cdot)\right\|_{1} \leqslant \varepsilon[\mu(A(\varepsilon))+\mu(B(\varepsilon))] \leqslant 2 \varepsilon\left(\theta-t_{0}\right) . \tag{2.6}
\end{equation*}
$$

Since $p \in\left(p_{*}-\delta_{1}\left(\varepsilon, H_{1}, H_{2}\right), p_{*}\right)$ and $u_{*}(\cdot) \in B_{p_{*}}^{H_{1}}\left(\mu_{0}\right)$ are arbitrarily chosen, (2.6) implies the validity of the proposition.

From Corollary 1.2 and Proposition 2.1 the validity of the following proposition follows.
Proposition 2.2. Let $p_{*}>1, \varepsilon \in\left(0, \alpha_{0}\right)$ where $\alpha_{0}>0$ is defined by (2.1). Then there exists $\gamma_{1}=\gamma_{1}(\varepsilon) \in\left(0, \frac{p_{*}-1}{2}\right]$ such that the inclusion

$$
B_{p_{*}}\left(\mu_{0}\right) \subset B_{p}\left(\mu_{0}\right)+\varepsilon B_{1}(1)
$$

holds for any $p \in\left(p_{*}-\gamma_{1}, p_{*}\right)$.
Proof. By Corollary 1.2 there exists $H_{*}(\varepsilon)>2 \mu_{0}$ such that for every $H>H_{*}(\varepsilon)$ the inclusions

$$
\begin{equation*}
B_{p}\left(\mu_{0}\right) \subset B_{p}^{H}\left(\mu_{0}\right)+\frac{\varepsilon}{3} B_{1}(1), \quad B_{p}^{H}\left(\mu_{0}\right) \subset B_{p}\left(\mu_{0}\right)+\frac{\varepsilon}{3} B_{1}(1) \tag{2.7}
\end{equation*}
$$

hold for any $p \in\left[\frac{p_{*}+1}{2}, 2 p_{*}\right]$.
Let $H_{1}(\varepsilon)=2 H_{*}(\varepsilon), H_{2}(\varepsilon)=3 H_{*}(\varepsilon)$. Then by virtue of Proposition 2.1 there exists $\gamma_{1}(\varepsilon)=$ $\delta_{1}\left(\varepsilon, H_{1}(\varepsilon), H_{2}(\varepsilon)\right) \in\left(0, \frac{p_{*}-1}{2}\right]$ such that the inclusion

$$
\begin{equation*}
B_{p_{*}}^{H_{1}(\varepsilon)}\left(\mu_{0}\right) \subset B_{p}^{H_{2}(\varepsilon)}\left(\mu_{0}\right)+\frac{\varepsilon}{3} B_{1}(1) \tag{2.8}
\end{equation*}
$$

holds for all $p \in\left(p_{*}-\gamma_{1}(\varepsilon), p_{*}\right)$.
The proof of the proposition follows from (2.7) and (2.8).
Now, let us give an upper estimation of the set $B_{p}^{H}\left(\mu_{0}\right)$ as $p \rightarrow p_{*}-0$. Let

$$
\begin{align*}
& \mu_{*}=\max \left\{\mu_{0}^{\frac{p_{*}-p}{p_{*}}}: p \in\left[\frac{p_{*}+1}{2}, p_{*}\right]\right\},  \tag{2.9}\\
& L_{*}=\left(2+\mu_{*}\right)\left(\theta-t_{0}\right) . \tag{2.10}
\end{align*}
$$

Proposition 2.3. Let $p_{*}>1, \varepsilon \in\left(0, \alpha_{0}\right), H>2 \mu_{0}$ where $\alpha_{0}>0$ is defined by (2.1). Then there exists $\delta_{2}=\delta_{2}(\varepsilon, H) \in\left(0, \frac{p_{*}-1}{2}\right]$ such that the inclusion

$$
B_{p}^{H}\left(\mu_{0}\right) \subset B_{p_{*}}^{H}\left(\mu_{0}\right)+L_{*} \varepsilon^{\frac{1}{2}} B_{1}(1)
$$

holds for any $p \in\left(p_{*}-\delta_{2}, p_{*}\right)$.
Proof. Let

$$
\delta_{2}(\varepsilon, H)=\min \left\{\beta_{3}(\varepsilon, H), \beta_{4}(\varepsilon, H)\right\}
$$

where

$$
\begin{aligned}
& \beta_{3}(\varepsilon, H)=\min \left\{p_{*} \log _{\frac{\mu_{0}}{\varepsilon}} \frac{H+\varepsilon}{H}, \frac{p_{*}-1}{2}\right\}, \\
& \beta_{4}(\varepsilon, H)=\min \left\{p_{*} \log _{\frac{\mu_{0}}{H}} \frac{H-\varepsilon}{H}, \frac{p_{*}-1}{2}\right\} .
\end{aligned}
$$

It is obvious that $\delta_{2}(\varepsilon, H) \in\left(0, \frac{p_{*}-1}{2}\right]$.
Let $p \in\left(p_{*}-\delta_{2}(\varepsilon, H), p_{*}\right)$. Now let us choose an arbitrary $u(\cdot) \in B_{p}^{H}\left(\mu_{0}\right)$ and define a function $u_{*}(\cdot):\left[t_{0}, \theta\right] \rightarrow R^{m}$ by setting

$$
\begin{equation*}
u_{*}(t)=u(t)\|u(t)\|^{\frac{p-p_{*}}{p_{*}}} \mu_{0} \frac{p_{*}-p}{p_{*}}, \quad t \in\left[t_{0}, \theta\right] . \tag{2.11}
\end{equation*}
$$

Since $u(\cdot) \in B_{p}^{H}\left(\mu_{0}\right)$ one can show that $u_{*}(\cdot) \in B_{p_{*}}^{H}\left(\mu_{0}\right)$.
Now let us set

$$
A(\varepsilon)=\left\{t \in\left[t_{0}, \theta\right]: 0 \leqslant\|u(t)\| \leqslant \varepsilon\right\}, \quad B(\varepsilon)=\left\{t \in\left[t_{0}, \theta\right]: \varepsilon<\|u(t)\| \leqslant H_{1}\right\} .
$$

Let $t \in A(\varepsilon)$. Then $0 \leqslant\|u(t)\| \leqslant \varepsilon$. Since $\varepsilon<\alpha_{0} \leqslant 1$ and $p \in\left(p_{*}-\delta_{2}(\varepsilon, H), p_{*}\right) \subset$ [ $\frac{p_{*}+1}{2}, p_{*}$ ) we get from (2.11)

$$
\begin{align*}
\int_{A(\varepsilon)}\left\|u(t)-u_{*}(t)\right\| d t & \leqslant \varepsilon\left(\theta-t_{0}\right)+\mu_{0}^{\frac{p_{*}-p}{p_{*}}} \varepsilon^{\frac{p}{p_{*}}}\left(\theta-t_{0}\right) \\
& \leqslant \varepsilon\left(\theta-t_{0}\right)+\varepsilon^{\frac{1}{2}} \mu_{*}\left(\theta-t_{0}\right) \\
& \leqslant \varepsilon^{\frac{1}{2}}\left(1+\mu_{*}\right)\left(\theta-t_{0}\right) \tag{2.12}
\end{align*}
$$

where $\mu_{*}$ is defined by (2.9).
Let $t \in B(\varepsilon)$. Then $\varepsilon<\|u(t)\| \leqslant H$ and

$$
\begin{equation*}
1-\left(\frac{\mu_{0}}{\varepsilon}\right)^{\frac{p_{*}-p}{p_{*}}} \leqslant 1-\left(\frac{\mu_{0}}{\|u(t)\|}\right)^{\frac{p_{*}-p}{p_{*}}} \leqslant 1-\left(\frac{\mu_{0}}{H}\right)^{\frac{p_{*}-p}{p_{*}}} . \tag{2.13}
\end{equation*}
$$

Since $p \in\left(p_{*}-\delta_{2}(\varepsilon, H), p_{*}\right)$ then (2.13) implies

$$
\left|1-\left(\frac{\mu_{0}}{\|u(t)\|}\right)^{\frac{p_{*}-p}{p_{*}}}\right| \leqslant \frac{\varepsilon}{H}
$$

and consequently

$$
\begin{equation*}
\|u(t)\|\left|1-\left(\frac{\mu_{0}}{\|u(t)\|}\right)^{\frac{p_{*}-p}{p_{*}}}\right| \leqslant \varepsilon \tag{2.14}
\end{equation*}
$$

for every $t \in B(\varepsilon)$. Thus, it follows from (2.12) and (2.14)

$$
\begin{aligned}
\left\|u(\cdot)-u_{*}(\cdot)\right\|_{1} & \leqslant \varepsilon^{\frac{1}{2}}\left(\theta-t_{0}\right)\left[1+\mu_{*}+\varepsilon^{\frac{1}{2}}\right] \\
& \leqslant \varepsilon^{\frac{1}{2}}\left(\theta-t_{0}\right)\left[2+\mu_{*}\right]=\varepsilon^{\frac{1}{2}} L_{*}
\end{aligned}
$$

where $L_{*}$ is defined by (2.10).
Since $p \in\left(p_{*}-\delta_{2}(\varepsilon, H), p_{*}\right)$ and $u(\cdot) \in B_{p}^{H}\left(\mu_{0}\right)$ are arbitrarily chosen, we obtain the validity of the proposition.

The following proposition gives an upper estimation of the set $B_{p}\left(\mu_{0}\right)$ as $p \rightarrow p_{*}-0$.

Proposition 2.4. Let $p_{*}>1, \varepsilon \in\left(0, \alpha_{0}\right)$ where $\alpha_{0}>0$ is defined by (2.1). Then there exists $\gamma_{2}=\gamma_{2}(\varepsilon) \in\left(0, \frac{p_{*}-1}{2}\right]$ such that the inclusion

$$
B_{p}\left(\mu_{0}\right) \subset B_{p_{*}}\left(\mu_{0}\right)+\varepsilon B_{1}(1)
$$

holds for any $p \in\left(p_{*}-\gamma_{2}, p_{*}\right)$.
Proof. By Corollary 1.2 there exists $H_{*}(\varepsilon)>2 \mu_{0}$ such that for all $H>H_{*}(\varepsilon)$ the inclusions

$$
\begin{equation*}
B_{p}\left(\mu_{0}\right) \subset B_{p}^{H}\left(\mu_{0}\right)+\frac{\varepsilon}{3} B_{1}(1), \quad B_{p}^{H}\left(\mu_{0}\right) \subset B_{p}\left(\mu_{0}\right)+\frac{\varepsilon}{3} B_{1}(1) \tag{2.15}
\end{equation*}
$$

hold for any $p \in\left[\frac{p_{*}+1}{2}, 2 p_{*}\right]$.
Let $H(\varepsilon)=2 H_{*}(\varepsilon)$. Then due to Proposition 2.3 there exists $\delta_{2}(\varepsilon)=\delta_{2}(\varepsilon, H(\varepsilon)) \in\left(0, \frac{p_{*}-1}{2}\right]$ such that the inclusion

$$
\begin{equation*}
B_{p}^{H(\varepsilon)}\left(\mu_{0}\right) \subset B_{p_{*}}^{H(\varepsilon)}\left(\mu_{0}\right)+\frac{\varepsilon}{3} B_{1}(1) \tag{2.16}
\end{equation*}
$$

holds for any $p \in\left(p_{*}-\delta_{2}(\varepsilon), p_{*}\right)$.
Let $\gamma_{2}=\gamma_{2}(\varepsilon)=\delta_{2}(\varepsilon)$. Then (2.15) and (2.16) complete the proof.
From Propositions 2.2 and 2.4 we get the following proposition.

Proposition 2.5. Let $p_{*}>1, \varepsilon \in\left(0, \alpha_{0}\right)$ where $\alpha_{0}>0$ is defined by (2.1). Then there exists $\delta_{*}=\delta_{*}(\varepsilon) \in\left(0, \frac{p_{*}-1}{2}\right]$ such that the inequality

$$
h_{1}\left(B_{p}\left(\mu_{0}\right), B_{p_{*}}\left(\mu_{0}\right)\right) \leqslant \varepsilon
$$

holds for all $p \in\left(p_{*}-\delta_{*}, p_{*}\right)$.

## 3. Right evaluation of $B_{p}\left(\mu_{0}\right)$

In this section we will study right continuity of the set-valued map $p \rightarrow B_{p}\left(\mu_{0}\right), p \in$ $(1,+\infty)$. The following proposition gives an upper estimation of the set $B_{p}^{H}\left(\mu_{0}\right)$ as $p \rightarrow p_{*}+0$.

Proposition 3.1. Let $p_{*}>1, \varepsilon \in\left(0, \alpha_{0}\right), H_{1}>H_{2}>\mu_{0}$ where $\alpha_{0}>0$ is defined by (2.1). Then, there exists $\nu_{1}=v_{1}\left(\varepsilon, H_{1}, H_{2}\right) \in\left(0, p_{*}\right]$ such that the inclusion

$$
B_{p}^{H_{2}}\left(\mu_{0}\right) \subset B_{p_{*}}^{H_{1}}\left(\mu_{0}\right)+2\left(\theta-t_{0}\right) \varepsilon B_{1}(1)
$$

holds for any $p \in\left(p_{*}, p_{*}+v_{1}\right)$.
Proof. Let

$$
\nu_{1}\left(\varepsilon, H_{1}, H_{2}\right)=\min \left\{\beta_{1}^{*}\left(\varepsilon, H_{1}, H_{2}\right), \beta_{2}^{*}\left(\varepsilon, H_{1}, H_{2}\right), p_{2}\left(H_{1}, H_{2}\right)-p_{*}\right\}
$$

where

$$
\begin{aligned}
& p_{2}\left(H_{1}, H_{2}\right)=\min \left\{2 p_{*}, p_{*}\left(1+\log _{\frac{H_{2}}{\mu_{0}}} \frac{H_{1}}{H_{2}}\right)\right\}, \\
& \beta_{1}^{*}\left(\varepsilon, H_{1}, H_{2}\right)=\min \left\{p_{*} \log _{\frac{H_{2}}{\mu_{0}}} \frac{H_{2}+\varepsilon}{H_{2}}, p_{*}\right\},
\end{aligned}
$$

$$
\beta_{2}^{*}\left(\varepsilon, H_{1}, H_{2}\right)=\min \left\{p_{*} \log _{\frac{\varepsilon}{\mu_{0}}} \frac{H_{2}-\varepsilon}{H_{2}}, p_{*}\right\} .
$$

It is obvious that $\nu_{1}\left(\varepsilon, H_{1}, H_{2}\right) \in\left(0, p_{*}\right]$.
Let $p \in\left(p_{*}, p_{*}+\nu_{1}\left(\varepsilon, H_{1}, H_{2}\right)\right)$ and choose an arbitrary $u(\cdot) \in B_{p}^{H_{2}}\left(\mu_{0}\right)$. Define a function $u_{*}(\cdot):\left[t_{0}, \theta\right] \rightarrow R^{m}$ by setting

$$
\begin{equation*}
u_{*}(t)=u(t)\|u(t)\|^{\frac{p-p *}{p *}} \mu_{0} \frac{p_{*}-p}{p_{*}}, \quad t \in\left[t_{0}, \theta\right] . \tag{3.1}
\end{equation*}
$$

It is not difficult to show that $u_{*}(\cdot) \in B_{p_{*}}^{H_{1}}\left(\mu_{0}\right)$.
Let us denote

$$
A(\varepsilon)=\left\{t \in\left[t_{0}, \theta\right]: 0 \leqslant\|u(t)\| \leqslant \varepsilon\right\}, \quad B(\varepsilon)=\left\{t \in\left[t_{0}, \theta\right]: \varepsilon<\|u(t)\| \leqslant H_{2}\right\} .
$$

Let $t \in A(\varepsilon)$. Since $\varepsilon<\mu_{0}$ and $p>p_{*}$ then we obtain

$$
\begin{equation*}
\|u(t)\|\left|1-\left(\frac{\|u(t)\|}{\mu_{0}}\right)^{\frac{p-p_{*}}{p_{*}}}\right| \leqslant \varepsilon . \tag{3.2}
\end{equation*}
$$

Let $t \in B(\varepsilon)$. Then $\varepsilon<\|u(t)\| \leqslant H_{2}$ and consequently

$$
\begin{equation*}
1-\left(\frac{H_{2}}{\mu_{0}}\right)^{\frac{p-p_{*}}{p_{*}}} \leqslant 1-\left(\frac{\|u(t)\|}{\mu_{0}}\right)^{\frac{p-p_{*}}{p_{*}}} \leqslant 1-\left(\frac{\varepsilon}{\mu_{0}}\right)^{\frac{p-p_{*}}{p_{*}}} . \tag{3.3}
\end{equation*}
$$

Since $p \in\left(p_{*}, p_{*}+v_{1}\left(\varepsilon, H_{1}, H_{2}\right)\right)$, from (3.3) we see that the inequality

$$
\left|1-\left(\frac{\|u(t)\|}{\mu_{0}}\right)^{\frac{p-p_{*}}{p_{*}}}\right| \leqslant \frac{\varepsilon}{H_{2}}
$$

is satisfied and hence

$$
\begin{equation*}
\|u(t)\|\left|1-\left(\frac{\|u(t)\|}{\mu_{0}}\right)^{\frac{p-p_{*}}{p_{*}}}\right| \leqslant \varepsilon . \tag{3.4}
\end{equation*}
$$

Thus, from (3.2) and (3.4) we obtain the inequality

$$
\left\|u(\cdot)-u_{*}(\cdot)\right\|_{1} \leqslant \varepsilon \mu(A(\varepsilon))+\varepsilon \mu(B(\varepsilon)) \leqslant 2 \varepsilon\left(\theta-t_{0}\right) .
$$

Since $p \in\left(p_{*}, p_{*}+v_{1}\left(\varepsilon, H_{1}, H_{2}\right)\right)$ and $u(\cdot) \in B_{p}^{H_{2}}\left(\mu_{0}\right)$ are arbitrarily chosen, the proof is completed.

Proposition 3.2. Let $p_{*}>1, \varepsilon \in\left(0, \alpha_{0}\right)$ where $\alpha_{0}>0$ is defined by (2.1). Then there exists $\gamma_{1}^{*}=\gamma_{1}^{*}(\varepsilon) \in\left(0, p_{*}\right]$ such that the inclusion

$$
B_{p}\left(\mu_{0}\right) \subset B_{p_{*}}\left(\mu_{0}\right)+\varepsilon B_{1}(1)
$$

holds for any $p \in\left(p_{*}, p_{*}+\gamma_{1}^{*}\right)$.
The proof of Proposition 3.2 follows from Corollary 1.2 and Proposition 3.1.
Let us define constants

$$
\begin{align*}
& \mu^{*}=\max \left\{\mu_{0}^{\frac{p-p_{*}}{p}}: p \in\left[p_{*}, 2 p_{*}\right]\right\},  \tag{3.5}\\
& L^{*}=\left(2+\mu^{*}\right)\left(\theta-t_{0}\right) \tag{3.6}
\end{align*}
$$

which are required in Proposition 3.3 and will be used in the sequel.

Proposition 3.3. Let $p_{*}>1, \varepsilon \in\left(0, \alpha_{0}\right)$ and $H>2 \mu_{0}$ where $\alpha_{0}>0$ is defined by (2.1). Then, there exists $\nu_{2}=\nu_{2}(\varepsilon, H) \in\left(0, p_{*}\right]$ such that the inclusion

$$
B_{p_{*}}^{H}\left(\mu_{0}\right) \subset B_{p}^{H}\left(\mu_{0}\right)+L_{*} \varepsilon^{\frac{1}{2}} B_{1}(1)
$$

holds for any $p \in\left(p_{*}, p_{*}+v_{2}\right)$.
Proof. Let

$$
\nu_{2}(\varepsilon, H)=\min \left\{\beta_{3}^{*}(\varepsilon, H), \beta_{4}^{*}(\varepsilon, H)\right\}
$$

where

$$
\begin{aligned}
& \beta_{3}^{*}(\varepsilon, H)=\min \left\{p_{*}\left(\frac{1}{1-\log _{\frac{\mu_{0}}{\varepsilon}} \frac{H+\varepsilon}{H}}-1\right), p_{*}\right\} \\
& \beta_{4}^{*}(\varepsilon, H)=\min \left\{p_{*}\left(\frac{1}{1-\log \frac{\mu_{0}}{H} \frac{H-\varepsilon}{H}}-1\right), p_{*}\right\} .
\end{aligned}
$$

It is obvious that $\nu_{2}(\varepsilon, H) \in\left(0, p_{*}\right]$.
Let $p \in\left(p_{*}, p_{*}+v_{2}(\varepsilon, H)\right)$ and $u_{*}(\cdot) \in B_{p_{*}}^{H}\left(\mu_{0}\right)$ be arbitrarily chosen. We set

$$
\begin{equation*}
u(t)=u_{*}(t)\left\|u_{*}(t)\right\|^{\frac{p_{*}-p}{p}} \mu_{0} \frac{p-p_{*}}{p}, \quad t \in\left[t_{0}, \theta\right] . \tag{3.7}
\end{equation*}
$$

It can be shown that $u(\cdot) \in B_{p}^{H}\left(\mu_{0}\right)$.
We denote

$$
A(\varepsilon)=\left\{t \in\left[t_{0}, \theta\right]: 0 \leqslant\left\|u_{*}(t)\right\| \leqslant \varepsilon\right\}, \quad B(\varepsilon)=\left\{t \in\left[t_{0}, \theta\right]: \varepsilon<\left\|u_{*}(t)\right\| \leqslant H\right\} .
$$

Let $t \in A(\varepsilon)$. Then $0 \leqslant\left\|u_{*}(t)\right\| \leqslant \varepsilon$. Since $\varepsilon<\alpha_{0}<1, p \in\left[p_{*}, 2 p_{*}\right]$ then we obtain that

$$
\begin{align*}
\int_{A(\varepsilon)}\left\|u_{*}(t)-u_{*}(t)\right\| u_{*}(t)\left\|^{\frac{p_{*}-p}{p}} \mu_{0}^{\frac{p-p_{*}}{p}}\right\| d t & \leqslant \varepsilon\left(\theta-t_{0}\right)+\mu_{0}^{\frac{p-p_{*}}{p}} \varepsilon^{\frac{p *}{p}}\left(\theta-t_{0}\right) \\
& \leqslant \varepsilon^{\frac{1}{2}}\left(1+\mu^{*}\right)\left(\theta-t_{0}\right) \tag{3.8}
\end{align*}
$$

where $\mu^{*}$ is defined by (3.5).
Let $t \in B(\varepsilon)$. Then, $\varepsilon<\left\|u_{*}(t)\right\| \leqslant H$ and consequently

$$
\begin{equation*}
1-\left(\frac{\mu_{0}}{\varepsilon}\right)^{\frac{p-p_{*}}{p}} \leqslant 1-\left(\frac{\mu_{0}}{\left\|u_{*}(t)\right\|}\right)^{\frac{p-p_{*}}{p}} \leqslant 1-\left(\frac{\mu_{0}}{H}\right)^{\frac{p-p_{*}}{p}} . \tag{3.9}
\end{equation*}
$$

Since $p \in\left(p_{*}, p_{*}+v_{2}(\varepsilon, H)\right)$ then from (3.9) we get

$$
\left|1-\left(\frac{\mu_{0}}{\left\|u_{*}(t)\right\|}\right)^{\frac{p-p_{*}}{p}}\right| \leqslant \frac{\varepsilon}{H_{2}}
$$

and hence

$$
\begin{equation*}
\left\|u_{*}(t)\right\|\left|1-\left(\frac{\mu_{0}}{\left\|u_{*}(t)\right\|}\right)^{\frac{p-p_{*}}{p}}\right| \leqslant \varepsilon \tag{3.10}
\end{equation*}
$$

for every $t \in B(\varepsilon)$. From (3.8) and (3.10) we conclude that

$$
\begin{aligned}
\left\|u(\cdot)-u_{*}(\cdot)\right\|_{1} & \leqslant \varepsilon^{\frac{1}{2}}\left(1+\mu^{*}\right)\left(\theta-t_{0}\right)+\varepsilon\left(\theta-t_{0}\right) \\
& \leqslant \varepsilon^{\frac{1}{2}}\left(\theta-t_{0}\right)\left[2+\mu^{*}\right]=\varepsilon^{\frac{1}{2}} L^{*}
\end{aligned}
$$

where $L^{*}$ is defined by (3.6).
Since $p \in\left(p_{*}, p_{*}+\nu_{2}(\varepsilon, H)\right)$ and $u_{*}(\cdot) \in B_{p_{*}}^{H}\left(\mu_{0}\right)$ are arbitrarily chosen, this completes the proof of the proposition.

Proposition 3.4. Let $p_{*}>1, \varepsilon \in\left(0, \alpha_{0}\right)$ where $\alpha_{0}>0$ is defined by (2.1). Then there exists $\gamma_{2}^{*}=\gamma_{2}^{*}(\varepsilon) \in\left(0, p_{*}\right]$ such that the inclusion

$$
B_{p_{*}}\left(\mu_{0}\right) \subset B_{p}\left(\mu_{0}\right)+\varepsilon B_{1}(1)
$$

holds for any $p \in\left(p_{*}, p_{*}+\gamma_{2}^{*}\right)$.
The proof of Proposition 3.4 follows from Corollary 1.2 and Proposition 3.3.
Propositions 3.2 and 3.4 imply the validity of the following proposition.
Proposition 3.5. Let $p_{*}>1$ and $\varepsilon \in\left(0, \alpha_{0}\right)$ where $\alpha_{0}>0$ is defined by (2.1). Then there exists $\delta^{*}=\delta^{*}(\varepsilon) \in\left(0, p_{*}\right]$ such that the inequality

$$
h_{1}\left(B_{p}\left(\mu_{0}\right), B_{p_{*}}\left(\mu_{0}\right)\right) \leqslant \varepsilon
$$

holds for all $p \in\left(p_{*}, p_{*}+\delta^{*}\right)$.
Finally, from Propositions 2.5 and 3.5 we obtain the validity of following theorem, which characterizes continuity of the set-valued map $p \rightarrow B_{p}\left(\mu_{0}\right)$ with respect to $p$ where $p \in(1+\infty)$.

Theorem 3.6. Let $p_{*}>1$ and $\varepsilon \in\left(0, \alpha_{0}\right)$ where $\alpha_{0}>0$ is defined by (2.1). Then there exists $\delta=\delta(\varepsilon)>0$ such that the inequality

$$
h_{1}\left(B_{p}\left(\mu_{0}\right), B_{p_{*}}\left(\mu_{0}\right)\right) \leqslant \varepsilon
$$

holds for all $p \in\left(p_{*}-\delta, p_{*}+\delta\right)$.

## 4. Attainable sets of control systems

Consider the control system the behavior of which is described by the differential equation

$$
\begin{equation*}
\dot{x}(t)=f(t, x(t), u(t)), \quad x\left(t_{0}\right) \in X_{0}, \tag{4.1}
\end{equation*}
$$

where $x \in R^{n}$ is the phase state vector of the system, $u \in R^{m}$ is the control vector, $t \in\left[t_{0}, \theta\right]$ is the time and $X_{0} \subset R^{n}$ is a compact set.

It is assumed that the right-hand side of the system (4.1) satisfies the following conditions:
(4.A) the function $f(\cdot):\left[t_{0}, \theta\right] \times R^{n} \times R^{m} \rightarrow R^{n}$ is continuous;
(4.B) for any bounded set $D \subset\left[t_{0}, \theta\right] \times R^{n}$ there exist constants $L_{1}=L_{1}(D)>0, L_{2}=$ $L_{2}(D)>0$ and $L_{3}=L_{3}(D)>0$ such that

$$
\left\|f\left(t, x_{1}, u_{1}\right)-f\left(t, x_{2}, u_{2}\right)\right\| \leqslant\left(L_{1}+L_{2}\left\|u_{2}\right\|\right)\left\|x_{1}-x_{2}\right\|+L_{3}\left\|u_{1}-u_{2}\right\|
$$

for any $\left(t, x_{1}\right) \in D,\left(t, x_{2}\right) \in D, u_{1} \in R^{m}$ and $u_{2} \in R^{m}$;
(4.C) There exists a constant $c>0$ such that

$$
\|f(t, x, u)\| \leqslant c(1+\|x\|)(1+\|u\|)
$$

for every $(t, x, u) \in\left[t_{0}, \theta\right] \times R^{n} \times R^{m}$.
The set $B_{p}\left(\mu_{0}\right)$ is called the set of admissible control functions and a function $u(\cdot) \in B_{p}\left(\mu_{0}\right)$ is said to be an admissible control function where the set $B_{p}\left(\mu_{0}\right)$ is defined by (1.1).

Let $u_{*}(\cdot) \in B_{p}\left(\mu_{0}\right)$. The absolutely continuous function $x_{*}(\cdot):\left[t_{0}, \theta\right] \rightarrow R^{n}$ which satisfies the equation $\dot{x}_{*}(t)=f\left(t, x_{*}(t), u_{*}(t)\right)$ a.e. in $\left[t_{0}, \theta\right]$ and the initial condition $x_{*}\left(t_{0}\right)=x_{0} \in X_{0}$ is said to be a solution of the system (4.1) with initial condition $x_{*}\left(t_{0}\right)=x_{0}$, generated by the admissible control function $u_{*}(\cdot)$. The symbol $x\left(\cdot ; t_{0}, x_{0}, u(\cdot)\right)$ denotes a solution of the system (4.1) with initial condition $x\left(t_{0}\right)=x_{0}$, generated by the admissible control function $u(\cdot)$.

Let us define the sets

$$
X_{p}\left(t_{0}, X_{0}, \mu_{0}\right)=\left\{x\left(\cdot ; t_{0}, x_{0}, u(\cdot)\right):\left[t_{0}, \theta\right] \rightarrow R^{n}: x_{0} \in X_{0}, u(\cdot) \in B_{p}\left(\mu_{0}\right)\right\}
$$

and

$$
X_{p}\left(t ; t_{0}, X_{0}, \mu_{0}\right)=\left\{x(t) \in R^{n}: x(\cdot) \in X_{p}\left(t_{0}, X_{0}, \mu_{0}\right)\right\}
$$

where $t \in\left[t_{0}, \theta\right]$.
The set $X_{p}\left(t ; t_{0}, X_{0}, \mu_{0}\right)$ is called the attainable set of the system (4.1) at the instant of time $t$. It is clear that the set $X_{p}\left(t ; t_{0}, X_{0}, \mu_{0}\right)$ consists of all $x \in R^{n}$ to which the system (4.1) can be steered at the instant of time $t \in\left[t_{0}, \theta\right]$. In general the set $X_{p}\left(t ; t_{0}, X_{0}, \mu_{0}\right) \subset R^{n}$ is not closed (see, e.g., [3]) and it is not difficult to verify that it depends on $t, t_{0}, X_{0}$ and $\mu_{0}$ continuously. Other properties of the attainable set $X_{p}\left(t ; t_{0}, X_{0}, \mu_{0}\right) \subset R^{n}$ and approximation methods for its numerical construction have been considered in [7,8,10-13]. In this section we show that the attainable set $X_{p}\left(t ; t_{0}, X_{0}, \mu_{0}\right) \subset R^{n}$ depends on $p$ continuously.

The following proposition characterizes boundedness of the attainable sets of the system (4.1).

## Proposition 4.1. The inequality

$$
\|x(t)\| \leqslant\left(\rho_{*}+r_{*}\right) \exp \left(r_{*}\right)
$$

holds for every $p \in(1,+\infty), x(\cdot) \in X_{p}\left(t_{0}, X_{0}, \mu_{0}\right)$ and $t \in\left[t_{0}, \theta\right]$ where

$$
\begin{equation*}
\rho_{*}=\max \left\{\|x\|: x \in X_{0}\right\}, \quad r_{*}=c r_{0}\left(1+\mu_{0}\right), \quad r_{0}=\max \left\{\theta-t_{0}, 1\right\} \tag{4.2}
\end{equation*}
$$

$c>0$ is defined by condition (4.C).
The proof of the proposition follows from conditions (4.A)-(4.C) and Gronwall inequality.
Denote

$$
\begin{equation*}
D=\left\{(t, x) \in\left[t_{0}, \theta\right] \times R^{n}:\|x\| \leqslant\left(\rho_{*}+r_{*}\right) \exp \left(r_{*}\right)\right\} \tag{4.3}
\end{equation*}
$$

where $\rho_{*}$ and $r_{*}$ are defined by (4.2).
According to Proposition 4.1 we get that $(t, x(t)) \in D$ for every $p \in(1,+\infty), x(\cdot) \in$ $X_{p}\left(t_{0}, X_{0}, \mu_{0}\right)$ and $t \in\left[t_{0}, \theta\right]$. Therefore, here and henceforth we will have in mind the cylinder (4.3) as the set $D$ in condition (4.B).

Note that the continuity property of the set-valued map $p \rightarrow B_{p}\left(\mu_{0}\right), p \in(1,+\infty)$, implies the uniform continuity (with respect to $t$ ) of the set-valued map $p \rightarrow X_{p}\left(t ; t_{0}, X_{0}, \mu_{0}\right)$, $p \in(1,+\infty)$.

Theorem 4.2. Let $p_{*}>1, \varepsilon \in\left(0, \alpha_{0}\right)$ where $\alpha_{0}>0$ is defined by (2.1). Then there exists $\xi=$ $\xi(\varepsilon)>0$ such that the inequality

$$
h_{c}\left(X_{p}\left(t_{0}, X_{0}, \mu_{0}\right), X_{p_{*}}\left(t_{0}, X_{0}, \mu_{0}\right)\right) \leqslant \varepsilon
$$

holds for any $p \in\left(p_{*}-\xi, p_{*}+\xi\right)$ and consequently for all $t \in\left[t_{0}, \theta\right]$

$$
h\left(X_{p}\left(t ; t_{0}, X_{0}, \mu_{0}\right), X_{p_{*}}\left(t ; t_{0}, X_{0}, \mu_{0}\right)\right) \leqslant \varepsilon
$$

Here $h_{c}(S, G)$ denotes the Hausdorff distance between the sets $S \subset C\left(\left[t_{0}, \theta\right] ; R^{n}\right)$ and $G \subset$ $C\left(\left[t_{0}, \theta\right] ; R^{n}\right)$ and is defined as

$$
h_{c}(S, G)=\max \left\{\sup _{x(\cdot) \in S} d_{c}(x(\cdot), G), \sup _{y(\cdot) \in G} d_{c}(y(\cdot), S)\right\}
$$

where $d_{c}(x(\cdot), G)=\inf \left\{\|x(\cdot)-y(\cdot)\|_{c}: y(\cdot) \in G\right\},\|z(\cdot)\|_{c}=\max \left\{\|z(t)\|: t \in\left[t_{0}, \theta\right]\right\}, C\left(\left[t_{0}, \theta\right]\right.$; $\left.R^{n}\right)$ is the space of continuous functions $x(\cdot):\left[t_{0}, \theta\right] \rightarrow R^{n}$.

Proof. Let

$$
\begin{equation*}
a_{0}=L_{1} r_{0}+L_{2} r_{0} \mu_{0}, \quad b_{0}=L_{3} \exp \left(a_{0}\right) \tag{4.4}
\end{equation*}
$$

where $r_{0}$ is defined by (4.2).
By virtue of Proposition 3.6 for $\frac{\varepsilon}{b_{0}}$ there exists $\xi=\xi(\varepsilon)$ such that the inequality

$$
\begin{equation*}
h_{1}\left(B_{p}\left(\mu_{0}\right), B_{p_{*}}\left(\mu_{0}\right)\right) \leqslant \frac{\varepsilon}{b_{0}} \tag{4.5}
\end{equation*}
$$

holds for all $p \in\left(p_{*}-\xi(\varepsilon), p_{*}+\xi(\varepsilon)\right)$.
Let us choose an arbitrary $p \in\left(p_{*}-\xi(\varepsilon), p_{*}+\xi(\varepsilon)\right)$ and $x(\cdot) \in X_{p}\left(t_{0}, X_{0}, \mu_{0}\right)$. Then there exist $x_{0} \in X_{0}$ and $u(\cdot) \in B_{p}\left(\mu_{0}\right)$ such that the equality

$$
\begin{equation*}
x(t)=x_{0}+\int_{t_{0}}^{t} f(\tau, x(\tau), u(\tau)) d \tau \tag{4.6}
\end{equation*}
$$

holds for every $t \in\left[t_{0}, \theta\right]$.
According to (4.5) there exists $u_{*}(\cdot) \in B_{p_{*}}\left(\mu_{0}\right)$ such that

$$
\begin{equation*}
\left\|u(\cdot)-u_{*}(\cdot)\right\|_{1} \leqslant \frac{\varepsilon}{b_{0}} \tag{4.7}
\end{equation*}
$$

Let

$$
\begin{equation*}
x_{*}(t)=x_{0}+\int_{t_{0}}^{t} f\left(\tau, x_{*}(\tau), u_{*}(\tau)\right) d \tau \tag{4.8}
\end{equation*}
$$

where $t \in\left[t_{0}, \theta\right]$. Then $x_{*}(\cdot) \in X_{p_{*}}\left(t_{0}, X_{0}, \mu_{0}\right)$. It follows from (4.B), (4.6)-(4.8) that

$$
\begin{equation*}
\left\|x(t)-x_{*}(t)\right\| \leqslant L_{3} \frac{\varepsilon}{b_{0}}+\int_{t_{0}}^{t}\left(L_{1}+L_{2}\left\|u_{*}(\tau)\right\|\right)\left\|x(\tau)-x_{*}(\tau)\right\| d \tau \tag{4.9}
\end{equation*}
$$

for all $t \in\left[t_{0}, \theta\right]$. From (4.4), (4.9) and Gronwall's inequality we obtain that the inequality

$$
\begin{align*}
\left\|x(t)-x_{*}(t)\right\| & \leqslant \frac{\varepsilon}{b_{0}} L_{3} \exp \left[\int_{t_{0}}^{\theta}\left(L_{1}+L_{2}\left\|u_{*}(\tau)\right\|\right) d \tau\right] \\
& =\frac{\varepsilon}{b_{0}} L_{3} \exp \left(a_{0}\right)=\varepsilon \tag{4.10}
\end{align*}
$$

holds for every $t \in\left[t_{0}, \theta\right]$. Since $p \in\left(p_{*}-\xi(\varepsilon), p_{*}+\xi(\varepsilon)\right)$ and $x(\cdot) \in X_{p}\left(t_{0}, X_{0}, \mu_{0}\right)$ are arbitrarily chosen, we get from (4.10) that

$$
\begin{equation*}
X_{p}\left(t_{0}, X_{0}, \mu_{0}\right) \subset X_{p_{*}}\left(t_{0}, X_{0}, \mu_{0}\right)+\varepsilon B_{c} \tag{4.11}
\end{equation*}
$$

holds for every $p \in\left(p_{*}-\xi(\varepsilon), p_{*}+\xi(\varepsilon)\right)$ where $B_{c}$ is unique ball of the space $C\left(\left[t_{0}, \theta\right] ; R^{n}\right)$.
Analogously, it is possible to prove that

$$
\begin{equation*}
X_{p_{*}}\left(t_{0}, X_{0}, \mu_{0}\right) \subset X_{p}\left(t_{0}, X_{0}, \mu_{0}\right)+\varepsilon B_{c} \tag{4.12}
\end{equation*}
$$

for every $p \in\left(p_{*}-\xi(\varepsilon), p_{*}+\xi(\varepsilon)\right)$.
Thus, inclusions (4.11) and (4.12) imply the validity of the theorem.

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