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J. Math. Anal. Appl. 335 (2007) 1347-1359

Journal of MATHEMATICAL ANALYSIS AND APPLICATIONS

www.elsevier.com/locate/jmaa

On the continuity property of L_p balls and an application $\stackrel{\approx}{\Rightarrow}$

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Submitted by M.A. Noor

Abstract

In this paper continuity properties of the set-valued map $p \to B_p(\mu_0)$, $p \in (1, +\infty)$, are considered where $B_p(\mu_0)$ is the closed ball of the space $L_p([t_0, \theta]; \mathbb{R}^m)$ centered at the origin with radius μ_0 . It is proved that the set-valued map $p \to B_p(\mu_0)$, $p \in (1, +\infty)$, is continuous. Applying obtained results, the attainable set of the nonlinear control system with integral constraint on the control is studied. The admissible control functions are chosen from $B_p(\mu_0)$. It is shown that the attainable set of the system is continuous with respect to p.

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Keywords: Lp space; Set-valued map; Control system; Attainable set

1. Introduction

Let $\|\cdot\|$ be Euclidean norm in \mathbb{R}^m , $\|u(\cdot)\|_p$ $(1 \leq p < +\infty)$ be a norm in $L_p([t_0, \theta], \mathbb{R}^m)$, where $L_p([t_0, \theta], \mathbb{R}^m)$ denotes the space of measurable functions $u(\cdot):[t_0, \theta] \to \mathbb{R}^m$ with bounded $\|u(\cdot)\|_p$ norm and

$$\left\| u(\cdot) \right\|_{p} = \left(\int_{t_{0}}^{\theta} \left\| u(t) \right\|^{p} dt \right)^{\frac{1}{p}}.$$

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0022-247X/\$ - see front matter © 2007 Elsevier Inc. All rights reserved. doi:10.1016/j.jmaa.2007.01.109

^{*} Supported by the Scientific and Technological Research Council of Turkey (TUBITAK) project No. 106T012.

For $p \ge 1$ and $\mu_0 > 0$ we set

$$B_p(\mu_0) = \left\{ u(\cdot) \in L_p([t_0, \theta], \mathbb{R}^m) \colon \left\| u(\cdot) \right\|_p \leq \mu_0 \right\}.$$

$$(1.1)$$

It is obvious that $B_p(\mu_0)$ is the closed ball centered at the origin with radius μ_0 in $L_p([t_0, \theta], \mathbb{R}^m)$.

The Hausdorff distance between the sets $A \subset R^m$ and $E \subset R^m$ is denoted by h(A, E) and is defined as

$$h(A, E) = \max\left\{\sup_{x \in A} d(x, E), \sup_{y \in E} d(y, A)\right\}$$

where $d(x, E) = \inf\{||x - y||: y \in E\}.$

The Hausdorff distance between the sets $U \subset L_{p_1}([t_0, \theta], \mathbb{R}^m)$ and $V \subset L_{p_2}([t_0, \theta], \mathbb{R}^m)$ is denoted by $h_1(U, V)$ and is defined as

$$h_1(U, V) = \max\left\{\sup_{x(\cdot)\in V} d_1(x(\cdot), U), \sup_{y(\cdot)\in U} d_1(y(\cdot), V)\right\}$$

where $d_1(x(\cdot), U) = \inf\{||x(\cdot) - y(\cdot)||_1: y(\cdot) \in U\}, p_1 \in [1, \infty), p_2 \in [1, \infty).$

For $\Omega \subset \mathbb{R}^n$ we denote by $\mu(\Omega)$ the Lebesgue measure of the set Ω .

The need to evaluate the distance between the sets arises in various problems of theory and applications (see, e.g., [1,2,4–6,8–10,13] and references therein).

In this paper, the Hausdorff distance between the sets $B_p(\mu_0)$ and $B_{p_*}(\mu_0)$ is studied where p > 1 and $p_* > 1$. In Section 2 we prove that $h_1(B_p(\mu_0), B_{p_*}(\mu_0)) \rightarrow 0$ as $p \rightarrow p_* - 0$ (Proposition 2.5). In Section 3 it is shown that $h_1(B_p(\mu_0), B_{p_*}(\mu_0)) \rightarrow 0$ as $p \rightarrow p_* + 0$ (Proposition 3.5). As a corollary of Propositions 2.5 and 3.5, Theorem 3.6 concludes that $h_1(B_p(\mu_0), B_{p_*}(\mu_0)) \rightarrow 0$ as $p \rightarrow p_*$. In Section 4 we consider attainable sets of the nonlinear control system with integral constraints on control. $B_p(\mu_0)$ is chosen as the set of admissible control functions. As an application of Theorem 3.6, it is proved that the attainable set of the control system is continuous with respect to p (Theorem 4.2).

Let $H \in (0, \infty)$. We set

$$B_p^H(\mu_0) = \left\{ u(\cdot) \in B_p(\mu_0) \colon \left\| u(t) \right\| \leq H \text{ for every } t \in [t_0, \theta] \right\}.$$

The following proposition characterizes the Hausdorff distance between the sets $B_p(\mu_0)$ and $B_p^H(\mu_0)$.

Proposition 1.1. Let p > 1, H > 0. Then the inequality

$$h_1(B_p(\mu_0), B_p^H(\mu_0)) \leq \frac{2\mu_0^p}{H^{p-1}}$$

holds.

Proof. Let us choose an arbitrary $u(\cdot) \in B_p(\mu_0)$ and define a function $u_*(\cdot) : [t_0, \theta] \to \mathbb{R}^m$, setting for $t \in [t_0, \theta]$

$$u_{*}(t) = \begin{cases} u(t), & \|u(t)\| \leq H, \\ \frac{u(t)}{\|u(t)\|} H, & \|u(t)\| > H. \end{cases}$$
(1.2)

It is not difficult to verify that $u_*(\cdot) \in B_p^H(\mu_0)$. Let

$$\Omega = \big\{ \tau \in [t_0, \theta] \colon \big\| u(\tau) \big\| > H \big\}.$$

Then using Hölder and Minkowski inequalities, we have from (1.2) that

$$\|u(\cdot) - u_*(\cdot)\|_1 = \int_{\Omega} \|u(t) - u_*(t)\| dt \leq 2\mu_0 \mu(\Omega)^{\frac{p-1}{p}}.$$
(1.3)

Since $u(\cdot) \in B_p(\mu_0)$ and $||u(\tau)|| > H$ for every $\tau \in \Omega$, we obtain

$$H^{p}\mu(\Omega) \leqslant \int_{\Omega} \left\| u(\tau) \right\|^{p} d\tau \leqslant \int_{t_{0}}^{\theta} \left\| u(\tau) \right\|^{p} d\tau \leqslant \mu_{0}^{p}$$

and consequently

$$\mu(\Omega) \leqslant \frac{\mu_0^p}{H^p}.\tag{1.4}$$

Then it follows from (1.3) and (1.4)

$$\|u(\cdot) - u_*(\cdot)\|_1 \leq 2\mu_0 \left(\frac{\mu_0^p}{H^p}\right)^{\frac{p-1}{p}} = \frac{2\mu_0^p}{H^{p-1}}.$$

Since $u(\cdot) \in B_p(\mu_0)$ is arbitrarily chosen, we get the inequality

$$\sup_{u(\cdot)\in B_p(\mu_0)} d_1(u(\cdot), B_p^H(\mu_0)) \leqslant \frac{2\mu_0^p}{H^{p-1}}.$$
(1.5)

Since $B_p^H(\mu_0) \subset B_p(\mu_0)$ then (1.5) completes the proof of the proposition. \Box

We obtain the following corollary from Proposition 1.1.

Corollary 1.2. Let $p_* > 1$ and $\varepsilon > 0$. Then there exists $H_*(\varepsilon) > 2\mu_0$ such that for all $H > H_*(\varepsilon)$ the inequality

$$h_1(B_p(\mu_0), B_p^H(\mu_0)) \leq \varepsilon$$

holds for any $p \in [\frac{p_*+1}{2}, 2p_*]$.

2. Left evaluation of $B_p(\mu_0)$

In this section, we will evaluate the Hausdorff distance between the sets $B_p(\mu_0)$ and $B_{p_*}(\mu_0)$ as $p \to p_* - 0$.

Let

$$\alpha_0 = \min\left\{\frac{\mu_0}{2}, 1\right\}.$$
(2.1)

Proposition 2.1. Let $p_* > 1$, $\varepsilon \in (0, \alpha_0)$ and $H_2 > H_1 > 2\mu_0$. Then there exists $\delta_1 = \delta_1(\varepsilon, H_1, H_2) \in (0, \frac{p_*-1}{2}]$ such that the inclusion

$$B_{p_*}^{H_1}(\mu_0) \subset B_p^{H_2}(\mu_0) + 2(\theta - t_0)\varepsilon B_1(1)$$

holds for all $p \in (p_* - \delta_1, p_*)$ where $\alpha_0 > 0$ is defined by (2.1) and $B_1(1)$ is defined by (1.1).

Proof. Let

$$\delta_1(\varepsilon, H_1, H_2) = \min\{\beta_1(\varepsilon, H_1), \beta_2(\varepsilon, H_1), p_* - p_1(H_1, H_2)\}$$

where

$$p_{1}(H_{1}, H_{2}) = \max\left\{\frac{p_{*}+1}{2}, \frac{p_{*}}{1+\log_{\frac{H_{1}}{\mu_{0}}}\frac{H_{2}}{H_{1}}}\right\}$$
$$\beta_{1}(\varepsilon, H_{1}) = p_{*}\left(1-\frac{1}{1+\log_{\frac{H_{1}}{\mu_{0}}}\frac{H_{1}+\varepsilon}{H_{1}}}\right),$$
$$\beta_{2}(\varepsilon, H_{1}) = p_{*}\left(1-\frac{1}{1+\log_{\frac{\varepsilon}{\mu_{0}}}\frac{H_{1}-\varepsilon}{H_{1}}}\right).$$

It is not difficult to verify that $\delta_1(\varepsilon, H_1, H_2) \in (0, \frac{p_*-1}{2}]$.

Let $u_*(\cdot) \in B_{p_*}^{H_1}(\mu_0)$ be arbitrarily chosen and $p \in (p_* - \delta_1(\varepsilon, H_1, H_2), p_*)$. We set

$$u_p(t) = u_*(t) \left\| u_*(t) \right\|^{\frac{p_* - p}{p}} \mu_0^{\frac{p - p_*}{p}}, \quad t \in [t_0, \theta].$$
(2.2)

Since $u_*(\cdot) \in B_{p_*}^{H_1}(\mu_0)$ and $p \in (p_* - \delta_1(\varepsilon, H_1, H_2), p_*)$, it is possible to prove that $u_p(\cdot) \in B_p^{H_2}(\mu_0)$.

Denote

$$A(\varepsilon) = \left\{ t \in [t_0, \theta] : 0 \leqslant \left\| u_*(t) \right\| \leqslant \varepsilon \right\}, \qquad B(\varepsilon) = \left\{ t \in [t_0, \theta] : \varepsilon < \left\| u_*(t) \right\| \leqslant H_1 \right\}.$$

Let $t \in A(\varepsilon)$. Then $0 \leq ||u_*(t)|| \leq \varepsilon$. Since $\varepsilon < \frac{\mu_0}{2}$ and $p < p_*$ then we obtain

$$\left\|u_{*}(t)\right\|\left|1-\left(\frac{\left\|u_{*}(t)\right\|}{\mu_{0}}\right)^{\frac{p_{*}-p}{p}}\right| \leq \varepsilon$$

$$(2.3)$$

for every $t \in A(\varepsilon)$.

Let $t \in B(\varepsilon)$. Then $\varepsilon < ||u_*(t)|| \leq H_1$ and this gives

$$1 - \left(\frac{H_1}{\mu_0}\right)^{\frac{p_*-p}{p}} \leqslant 1 - \left(\frac{\|u_*(t)\|}{\mu_0}\right)^{\frac{p_*-p}{p}} \leqslant 1 - \left(\frac{\varepsilon}{\mu_0}\right)^{\frac{p_*-p}{p}}.$$
(2.4)

Since $p \in (p_* - \delta_1(\varepsilon, H_1, H_2), p_*)$, then we get from (2.4) that the inequality

$$\left|1 - \left(\frac{\|u_*(t)\|}{\mu_0}\right)^{\frac{p_*-p}{p}}\right| \leqslant \frac{\varepsilon}{H_1}$$

holds for every $t \in B(\varepsilon)$ and consequently

$$\left\|u_{*}(t)\right\|\left|1-\left(\frac{\left\|u_{*}(t)\right\|}{\mu_{0}}\right)^{\frac{p_{*}-p}{p}}\right| \leq \varepsilon.$$
(2.5)

Finally, it follows from (2.3) and (2.5) that

$$\left\| u_{p}(\cdot) - u_{*}(\cdot) \right\|_{1} \leq \varepsilon \left[\mu \left(A(\varepsilon) \right) + \mu \left(B(\varepsilon) \right) \right] \leq 2\varepsilon (\theta - t_{0}).$$

$$(2.6)$$

Since $p \in (p_* - \delta_1(\varepsilon, H_1, H_2), p_*)$ and $u_*(\cdot) \in B_{p_*}^{H_1}(\mu_0)$ are arbitrarily chosen, (2.6) implies the validity of the proposition. \Box

From Corollary 1.2 and Proposition 2.1 the validity of the following proposition follows.

Proposition 2.2. Let $p_* > 1$, $\varepsilon \in (0, \alpha_0)$ where $\alpha_0 > 0$ is defined by (2.1). Then there exists $\gamma_1 = \gamma_1(\varepsilon) \in (0, \frac{p_*-1}{2}]$ such that the inclusion

$$B_{p_*}(\mu_0) \subset B_p(\mu_0) + \varepsilon B_1(1)$$

holds for any $p \in (p_* - \gamma_1, p_*)$.

Proof. By Corollary 1.2 there exists $H_*(\varepsilon) > 2\mu_0$ such that for every $H > H_*(\varepsilon)$ the inclusions

$$B_p(\mu_0) \subset B_p^H(\mu_0) + \frac{\varepsilon}{3} B_1(1), \qquad B_p^H(\mu_0) \subset B_p(\mu_0) + \frac{\varepsilon}{3} B_1(1)$$
 (2.7)

hold for any $p \in [\frac{p_*+1}{2}, 2p_*]$. Let $H_1(\varepsilon) = 2H_*(\varepsilon), H_2(\varepsilon) = 3H_*(\varepsilon)$. Then by virtue of Proposition 2.1 there exists $\gamma_1(\varepsilon) = \delta_1(\varepsilon, H_1(\varepsilon), H_2(\varepsilon)) \in (0, \frac{p_*-1}{2}]$ such that the inclusion

$$B_{p_*}^{H_1(\varepsilon)}(\mu_0) \subset B_p^{H_2(\varepsilon)}(\mu_0) + \frac{\varepsilon}{3}B_1(1)$$
(2.8)

holds for all $p \in (p_* - \gamma_1(\varepsilon), p_*)$.

The proof of the proposition follows from (2.7) and (2.8). \Box

Now, let us give an upper estimation of the set $B_p^H(\mu_0)$ as $p \to p_* - 0$. Let

$$\mu_* = \max\left\{\mu_0^{\frac{p_*-p}{p_*}}: \ p \in \left[\frac{p_*+1}{2}, \ p_*\right]\right\},\tag{2.9}$$

$$L_* = (2 + \mu_*)(\theta - t_0). \tag{2.10}$$

Proposition 2.3. Let $p_* > 1$, $\varepsilon \in (0, \alpha_0)$, $H > 2\mu_0$ where $\alpha_0 > 0$ is defined by (2.1). Then there exists $\delta_2 = \delta_2(\varepsilon, H) \in (0, \frac{p_*-1}{2}]$ such that the inclusion

$$B_p^H(\mu_0) \subset B_{p_*}^H(\mu_0) + L_* \varepsilon^{\frac{1}{2}} B_1(1)$$

holds for any $p \in (p_* - \delta_2, p_*)$ *.*

Proof. Let

$$\delta_2(\varepsilon, H) = \min\{\beta_3(\varepsilon, H), \beta_4(\varepsilon, H)\}$$

where

$$\beta_3(\varepsilon, H) = \min\left\{p_* \log_{\frac{\mu_0}{\varepsilon}} \frac{H + \varepsilon}{H}, \frac{p_* - 1}{2}\right\},\$$

$$\beta_4(\varepsilon, H) = \min\left\{p_* \log_{\frac{\mu_0}{H}} \frac{H - \varepsilon}{H}, \frac{p_* - 1}{2}\right\}.$$

It is obvious that $\delta_2(\varepsilon, H) \in (0, \frac{p_*-1}{2}]$.

Let $p \in (p_* - \delta_2(\varepsilon, H), p_*)$. Now let us choose an arbitrary $u(\cdot) \in B_p^H(\mu_0)$ and define a function $u_*(\cdot) : [t_0, \theta] \to \mathbb{R}^m$ by setting

$$u_{*}(t) = u(t) \left\| u(t) \right\|^{\frac{p-p_{*}}{p_{*}}} \mu_{0}^{\frac{p_{*}-p}{p_{*}}}, \quad t \in [t_{0}, \theta].$$
(2.11)

Since $u(\cdot) \in B_p^H(\mu_0)$ one can show that $u_*(\cdot) \in B_{p_*}^H(\mu_0)$. Now let us set

$$A(\varepsilon) = \left\{ t \in [t_0, \theta] \colon 0 \leq \left\| u(t) \right\| \leq \varepsilon \right\}, \qquad B(\varepsilon) = \left\{ t \in [t_0, \theta] \colon \varepsilon < \left\| u(t) \right\| \leq H_1 \right\}.$$

Let $t \in A(\varepsilon)$. Then $0 \leq ||u(t)|| \leq \varepsilon$. Since $\varepsilon < \alpha_0 \leq 1$ and $p \in (p_* - \delta_2(\varepsilon, H), p_*) \subset [\frac{p_*+1}{2}, p_*)$ we get from (2.11)

$$\int_{A(\varepsilon)} \left\| u(t) - u_{*}(t) \right\| dt \leqslant \varepsilon(\theta - t_{0}) + \mu_{0}^{\frac{p_{*}-p}{p_{*}}} \varepsilon^{\frac{p}{p_{*}}}(\theta - t_{0})$$

$$\leqslant \varepsilon(\theta - t_{0}) + \varepsilon^{\frac{1}{2}} \mu_{*}(\theta - t_{0})$$

$$\leqslant \varepsilon^{\frac{1}{2}}(1 + \mu_{*})(\theta - t_{0})$$
(2.12)

where μ_* is defined by (2.9).

Let $t \in B(\varepsilon)$. Then $\varepsilon < ||u(t)|| \leq H$ and

$$1 - \left(\frac{\mu_0}{\varepsilon}\right)^{\frac{p_* - p}{p_*}} \leqslant 1 - \left(\frac{\mu_0}{\|u(t)\|}\right)^{\frac{p_* - p}{p_*}} \leqslant 1 - \left(\frac{\mu_0}{H}\right)^{\frac{p_* - p}{p_*}}.$$
(2.13)

Since $p \in (p_* - \delta_2(\varepsilon, H), p_*)$ then (2.13) implies

$$\left|1 - \left(\frac{\mu_0}{\|u(t)\|}\right)^{\frac{p_* - p}{p_*}}\right| \leqslant \frac{\varepsilon}{H}$$

and consequently

$$\left\|u(t)\right\| \left|1 - \left(\frac{\mu_0}{\|u(t)\|}\right)^{\frac{p_* - p}{p_*}}\right| \leqslant \varepsilon$$
(2.14)

for every $t \in B(\varepsilon)$. Thus, it follows from (2.12) and (2.14)

$$\begin{aligned} \left\| u(\cdot) - u_*(\cdot) \right\|_1 &\leq \varepsilon^{\frac{1}{2}} (\theta - t_0) \left[1 + \mu_* + \varepsilon^{\frac{1}{2}} \right] \\ &\leq \varepsilon^{\frac{1}{2}} (\theta - t_0) [2 + \mu_*] = \varepsilon^{\frac{1}{2}} L_* \end{aligned}$$

where L_* is defined by (2.10).

Since $p \in (p_* - \delta_2(\varepsilon, H), p_*)$ and $u(\cdot) \in B_p^H(\mu_0)$ are arbitrarily chosen, we obtain the validity of the proposition. \Box

The following proposition gives an upper estimation of the set $B_p(\mu_0)$ as $p \to p_* - 0$.

Proposition 2.4. Let $p_* > 1$, $\varepsilon \in (0, \alpha_0)$ where $\alpha_0 > 0$ is defined by (2.1). Then there exists $\gamma_2 = \gamma_2(\varepsilon) \in (0, \frac{p_*-1}{2}]$ such that the inclusion

$$B_p(\mu_0) \subset B_{p_*}(\mu_0) + \varepsilon B_1(1)$$

holds for any $p \in (p_* - \gamma_2, p_*)$ *.*

Proof. By Corollary 1.2 there exists $H_*(\varepsilon) > 2\mu_0$ such that for all $H > H_*(\varepsilon)$ the inclusions

$$B_p(\mu_0) \subset B_p^H(\mu_0) + \frac{\varepsilon}{3} B_1(1), \qquad B_p^H(\mu_0) \subset B_p(\mu_0) + \frac{\varepsilon}{3} B_1(1)$$
 (2.15)

hold for any $p \in [\frac{p_*+1}{2}, 2p_*]$.

Let $H(\varepsilon) = 2H_*(\varepsilon)$. Then due to Proposition 2.3 there exists $\delta_2(\varepsilon) = \delta_2(\varepsilon, H(\varepsilon)) \in (0, \frac{p_*-1}{2}]$ such that the inclusion

$$B_{p}^{H(\varepsilon)}(\mu_{0}) \subset B_{p_{*}}^{H(\varepsilon)}(\mu_{0}) + \frac{\varepsilon}{3}B_{1}(1)$$
(2.16)

holds for any $p \in (p_* - \delta_2(\varepsilon), p_*)$.

Let $\gamma_2 = \gamma_2(\varepsilon) = \delta_2(\varepsilon)$. Then (2.15) and (2.16) complete the proof. \Box

From Propositions 2.2 and 2.4 we get the following proposition.

Proposition 2.5. Let $p_* > 1$, $\varepsilon \in (0, \alpha_0)$ where $\alpha_0 > 0$ is defined by (2.1). Then there exists $\delta_* = \delta_*(\varepsilon) \in (0, \frac{p_*-1}{2}]$ such that the inequality

$$h_1(B_p(\mu_0), B_{p_*}(\mu_0)) \leq \varepsilon$$

holds for all $p \in (p_* - \delta_*, p_*)$ *.*

3. Right evaluation of $B_p(\mu_0)$

In this section we will study right continuity of the set-valued map $p \to B_p(\mu_0), p \in (1, +\infty)$. The following proposition gives an upper estimation of the set $B_p^H(\mu_0)$ as $p \to p_* + 0$.

Proposition 3.1. Let $p_* > 1$, $\varepsilon \in (0, \alpha_0)$, $H_1 > H_2 > \mu_0$ where $\alpha_0 > 0$ is defined by (2.1). Then, there exists $v_1 = v_1(\varepsilon, H_1, H_2) \in (0, p_*]$ such that the inclusion

$$B_{p}^{H_{2}}(\mu_{0}) \subset B_{p_{*}}^{H_{1}}(\mu_{0}) + 2(\theta - t_{0})\varepsilon B_{1}(1)$$

holds for any $p \in (p_*, p_* + v_1)$ *.*

Proof. Let

$$\nu_1(\varepsilon, H_1, H_2) = \min\{\beta_1^*(\varepsilon, H_1, H_2), \beta_2^*(\varepsilon, H_1, H_2), p_2(H_1, H_2) - p_*\}$$

where

$$p_{2}(H_{1}, H_{2}) = \min\left\{2p_{*}, p_{*}\left(1 + \log_{\frac{H_{2}}{\mu_{0}}}\frac{H_{1}}{H_{2}}\right)\right\}$$
$$\beta_{1}^{*}(\varepsilon, H_{1}, H_{2}) = \min\left\{p_{*}\log_{\frac{H_{2}}{\mu_{0}}}\frac{H_{2} + \varepsilon}{H_{2}}, p_{*}\right\},$$

$$\beta_2^*(\varepsilon, H_1, H_2) = \min\left\{p_* \log_{\frac{\varepsilon}{\mu_0}} \frac{H_2 - \varepsilon}{H_2}, p_*\right\}$$

It is obvious that $v_1(\varepsilon, H_1, H_2) \in (0, p_*]$.

Let $p \in (p_*, p_* + v_1(\varepsilon, H_1, H_2))$ and choose an arbitrary $u(\cdot) \in B_p^{H_2}(\mu_0)$. Define a function $u_*(\cdot) : [t_0, \theta] \to R^m$ by setting

$$u_{*}(t) = u(t) \left\| u(t) \right\|^{\frac{p-p_{*}}{p_{*}}} \mu_{0}^{\frac{p_{*}-p}{p_{*}}}, \quad t \in [t_{0}, \theta].$$
(3.1)

It is not difficult to show that $u_*(\cdot) \in B_{p_*}^{H_1}(\mu_0)$. Let us denote

$$A(\varepsilon) = \left\{ t \in [t_0, \theta] : \ 0 \le \left\| u(t) \right\| \le \varepsilon \right\}, \qquad B(\varepsilon) = \left\{ t \in [t_0, \theta] : \varepsilon < \left\| u(t) \right\| \le H_2 \right\}.$$

Let $t \in A(\varepsilon)$. Since $\varepsilon < \mu_0$ and $p > p_*$ then we obtain

$$\left\| u(t) \right\| \left| 1 - \left(\frac{\| u(t) \|}{\mu_0} \right)^{\frac{p-p_*}{p_*}} \right| \le \varepsilon.$$

$$(3.2)$$

Let $t \in B(\varepsilon)$. Then $\varepsilon < ||u(t)|| \leq H_2$ and consequently

$$1 - \left(\frac{H_2}{\mu_0}\right)^{\frac{p-p_*}{p_*}} \leqslant 1 - \left(\frac{\|u(t)\|}{\mu_0}\right)^{\frac{p-p_*}{p_*}} \leqslant 1 - \left(\frac{\varepsilon}{\mu_0}\right)^{\frac{p-p_*}{p_*}}.$$
(3.3)

Since $p \in (p_*, p_* + v_1(\varepsilon, H_1, H_2))$, from (3.3) we see that the inequality

$$\left|1 - \left(\frac{\|u(t)\|}{\mu_0}\right)^{\frac{p-p_*}{p_*}}\right| \leq \frac{\varepsilon}{H_2}$$

is satisfied and hence

$$\left\| u(t) \right\| \left| 1 - \left(\frac{\|u(t)\|}{\mu_0} \right)^{\frac{p-p_*}{p_*}} \right| \leq \varepsilon.$$
(3.4)

Thus, from (3.2) and (3.4) we obtain the inequality

$$\| u(\cdot) - u_*(\cdot) \|_1 \leq \varepsilon \mu (A(\varepsilon)) + \varepsilon \mu (B(\varepsilon)) \leq 2\varepsilon (\theta - t_0).$$

Since $p \in (p_*, p_* + \nu_1(\varepsilon, H_1, H_2))$ and $u(\cdot) \in B_p^{H_2}(\mu_0)$ are arbitrarily chosen, the proof is completed. \Box

Proposition 3.2. Let $p_* > 1$, $\varepsilon \in (0, \alpha_0)$ where $\alpha_0 > 0$ is defined by (2.1). Then there exists $\gamma_1^* = \gamma_1^*(\varepsilon) \in (0, p_*]$ such that the inclusion

$$B_p(\mu_0) \subset B_{p_*}(\mu_0) + \varepsilon B_1(1)$$

holds for any $p \in (p_*, p_* + \gamma_1^*)$ *.*

The proof of Proposition 3.2 follows from Corollary 1.2 and Proposition 3.1.

Let us define constants

$$\mu^* = \max\left\{\mu_0^{\frac{p-p_*}{p}} \colon p \in [p_*, 2p_*]\right\},$$

$$L^* = (2 + \mu^*)(\theta - t_0)$$
(3.5)
(3.6)

which are required in Proposition 3.3 and will be used in the sequel.

Proposition 3.3. Let $p_* > 1$, $\varepsilon \in (0, \alpha_0)$ and $H > 2\mu_0$ where $\alpha_0 > 0$ is defined by (2.1). Then, there exists $v_2 = v_2(\varepsilon, H) \in (0, p_*]$ such that the inclusion

$$B_{p_*}^H(\mu_0) \subset B_p^H(\mu_0) + L_* \varepsilon^{\frac{1}{2}} B_1(1)$$

holds for any $p \in (p_*, p_* + v_2)$ *.*

Proof. Let

$$\nu_2(\varepsilon, H) = \min\{\beta_3^*(\varepsilon, H), \beta_4^*(\varepsilon, H)\}$$

where

$$\begin{split} \beta_3^*(\varepsilon, H) &= \min\left\{p_*\left(\frac{1}{1 - \log\frac{\mu_0}{\varepsilon}} \frac{H + \varepsilon}{H} - 1\right), p_*\right\},\\ \beta_4^*(\varepsilon, H) &= \min\left\{p_*\left(\frac{1}{1 - \log\frac{\mu_0}{H}} \frac{H - \varepsilon}{H} - 1\right), p_*\right\}. \end{split}$$

It is obvious that $v_2(\varepsilon, H) \in (0, p_*]$.

Let $p \in (p_*, p_* + \nu_2(\varepsilon, H))$ and $u_*(\cdot) \in B_{p_*}^H(\mu_0)$ be arbitrarily chosen. We set

$$u(t) = u_*(t) \left\| u_*(t) \right\|^{\frac{p_*-p}{p}} \mu_0^{\frac{p-p_*}{p}}, \quad t \in [t_0, \theta].$$
(3.7)

It can be shown that $u(\cdot) \in B_p^H(\mu_0)$.

We denote

$$A(\varepsilon) = \left\{ t \in [t_0, \theta] \colon 0 \leqslant \left\| u_*(t) \right\| \leqslant \varepsilon \right\}, \qquad B(\varepsilon) = \left\{ t \in [t_0, \theta] \colon \varepsilon < \left\| u_*(t) \right\| \leqslant H \right\}.$$

Let $t \in A(\varepsilon)$. Then $0 \leq ||u_*(t)|| \leq \varepsilon$. Since $\varepsilon < \alpha_0 < 1$, $p \in [p_*, 2p_*]$ then we obtain that

$$\int_{A(\varepsilon)} \|u_{*}(t) - u_{*}(t)\| \|u_{*}(t)\| \|^{\frac{p*-p}{p}} \mu_{0}^{\frac{p-p*}{p}} \|dt \leq \varepsilon(\theta - t_{0}) + \mu_{0}^{\frac{p-p*}{p}} \varepsilon^{\frac{p*}{p}}(\theta - t_{0})$$
$$\leq \varepsilon^{\frac{1}{2}} (1 + \mu^{*})(\theta - t_{0})$$
(3.8)

where μ^* is defined by (3.5).

Let $t \in B(\varepsilon)$. Then, $\varepsilon < ||u_*(t)|| \leq H$ and consequently

$$1 - \left(\frac{\mu_0}{\varepsilon}\right)^{\frac{p-p_*}{p}} \leqslant 1 - \left(\frac{\mu_0}{\|u_*(t)\|}\right)^{\frac{p-p_*}{p}} \leqslant 1 - \left(\frac{\mu_0}{H}\right)^{\frac{p-p_*}{p}}.$$
(3.9)

Since $p \in (p_*, p_* + v_2(\varepsilon, H))$ then from (3.9) we get

$$\left|1 - \left(\frac{\mu_0}{\|u_*(t)\|}\right)^{\frac{p-p_*}{p}}\right| \leqslant \frac{\varepsilon}{H_2}$$

and hence

$$\left\|u_{*}(t)\right\|\left|1-\left(\frac{\mu_{0}}{\left\|u_{*}(t)\right\|}\right)^{\frac{p-p_{*}}{p}}\right| \leq \varepsilon$$
(3.10)

for every $t \in B(\varepsilon)$. From (3.8) and (3.10) we conclude that

$$\begin{aligned} \left\| u(\cdot) - u_*(\cdot) \right\|_1 &\leq \varepsilon^{\frac{1}{2}} (1 + \mu^*) (\theta - t_0) + \varepsilon (\theta - t_0) \\ &\leq \varepsilon^{\frac{1}{2}} (\theta - t_0) [2 + \mu^*] = \varepsilon^{\frac{1}{2}} L^* \end{aligned}$$

where L^* is defined by (3.6).

Since $p \in (p_*, p_* + v_2(\varepsilon, H))$ and $u_*(\cdot) \in B_{p_*}^H(\mu_0)$ are arbitrarily chosen, this completes the proof of the proposition. \Box

Proposition 3.4. Let $p_* > 1$, $\varepsilon \in (0, \alpha_0)$ where $\alpha_0 > 0$ is defined by (2.1). Then there exists $\gamma_2^* = \gamma_2^*(\varepsilon) \in (0, p_*]$ such that the inclusion

 $B_{p_*}(\mu_0) \subset B_p(\mu_0) + \varepsilon B_1(1)$

holds for any $p \in (p_*, p_* + \gamma_2^*)$ *.*

The proof of Proposition 3.4 follows from Corollary 1.2 and Proposition 3.3. Propositions 3.2 and 3.4 imply the validity of the following proposition.

Proposition 3.5. Let $p_* > 1$ and $\varepsilon \in (0, \alpha_0)$ where $\alpha_0 > 0$ is defined by (2.1). Then there exists $\delta^* = \delta^*(\varepsilon) \in (0, p_*]$ such that the inequality

 $h_1(B_p(\mu_0), B_{p_*}(\mu_0)) \leq \varepsilon$

holds for all $p \in (p_*, p_* + \delta^*)$ *.*

Finally, from Propositions 2.5 and 3.5 we obtain the validity of following theorem, which characterizes continuity of the set-valued map $p \rightarrow B_p(\mu_0)$ with respect to p where $p \in (1+\infty)$.

Theorem 3.6. Let $p_* > 1$ and $\varepsilon \in (0, \alpha_0)$ where $\alpha_0 > 0$ is defined by (2.1). Then there exists $\delta = \delta(\varepsilon) > 0$ such that the inequality

 $h_1(B_p(\mu_0), B_{p_*}(\mu_0)) \leq \varepsilon$

holds for all $p \in (p_* - \delta, p_* + \delta)$ *.*

4. Attainable sets of control systems

Consider the control system the behavior of which is described by the differential equation

$$\dot{x}(t) = f(t, x(t), u(t)), \qquad x(t_0) \in X_0,$$
(4.1)

where $x \in \mathbb{R}^n$ is the phase state vector of the system, $u \in \mathbb{R}^m$ is the control vector, $t \in [t_0, \theta]$ is the time and $X_0 \subset \mathbb{R}^n$ is a compact set.

It is assumed that the right-hand side of the system (4.1) satisfies the following conditions:

(4.A) the function $f(\cdot):[t_0,\theta] \times \mathbb{R}^n \times \mathbb{R}^m \to \mathbb{R}^n$ is continuous;

(4.B) for any bounded set $D \subset [t_0, \theta] \times \mathbb{R}^n$ there exist constants $L_1 = L_1(D) > 0$, $L_2 = L_2(D) > 0$ and $L_3 = L_3(D) > 0$ such that

$$\left\|f(t, x_1, u_1) - f(t, x_2, u_2)\right\| \leq \left(L_1 + L_2 \|u_2\|\right) \|x_1 - x_2\| + L_3 \|u_1 - u_2\|$$

for any $(t, x_1) \in D$, $(t, x_2) \in D$, $u_1 \in R^m$ and $u_2 \in R^m$;

(4.C) There exists a constant c > 0 such that

$$\left\| f(t, x, u) \right\| \leq c \left(1 + \|x\| \right) \left(1 + \|u\| \right)$$

for every $(t, x, u) \in [t_0, \theta] \times \mathbb{R}^n \times \mathbb{R}^m$.

The set $B_p(\mu_0)$ is called the set of admissible control functions and a function $u(\cdot) \in B_p(\mu_0)$ is said to be an admissible control function where the set $B_p(\mu_0)$ is defined by (1.1).

Let $u_*(\cdot) \in B_p(\mu_0)$. The absolutely continuous function $x_*(\cdot) : [t_0, \theta] \to \mathbb{R}^n$ which satisfies the equation $\dot{x}_*(t) = f(t, x_*(t), u_*(t))$ a.e. in $[t_0, \theta]$ and the initial condition $x_*(t_0) = x_0 \in X_0$ is said to be a solution of the system (4.1) with initial condition $x_*(t_0) = x_0$, generated by the admissible control function $u_*(\cdot)$. The symbol $x(\cdot; t_0, x_0, u(\cdot))$ denotes a solution of the system (4.1) with initial condition $x(t_0) = x_0$, generated by the admissible control function $u(\cdot)$.

Let us define the sets

$$X_p(t_0, X_0, \mu_0) = \left\{ x(\cdot; t_0, x_0, u(\cdot)) : [t_0, \theta] \to \mathbb{R}^n : x_0 \in X_0, \ u(\cdot) \in B_p(\mu_0) \right\}$$

and

$$X_p(t; t_0, X_0, \mu_0) = \left\{ x(t) \in \mathbb{R}^n \colon x(\cdot) \in X_p(t_0, X_0, \mu_0) \right\}$$

where $t \in [t_0, \theta]$.

The set $X_p(t; t_0, X_0, \mu_0)$ is called the attainable set of the system (4.1) at the instant of time t. It is clear that the set $X_p(t; t_0, X_0, \mu_0)$ consists of all $x \in \mathbb{R}^n$ to which the system (4.1) can be steered at the instant of time $t \in [t_0, \theta]$. In general the set $X_p(t; t_0, X_0, \mu_0) \subset \mathbb{R}^n$ is not closed (see, e.g., [3]) and it is not difficult to verify that it depends on t, t_0, X_0 and μ_0 continuously. Other properties of the attainable set $X_p(t; t_0, X_0, \mu_0) \subset \mathbb{R}^n$ and approximation methods for its numerical construction have been considered in [7,8,10–13]. In this section we show that the attainable set $X_p(t; t_0, X_0, \mu_0) \subset \mathbb{R}^n$ depends on p continuously.

The following proposition characterizes boundedness of the attainable sets of the system (4.1).

Proposition 4.1. The inequality

$$\|x(t)\| \leq (\rho_* + r_*) \exp(r_*)$$

holds for every $p \in (1, +\infty)$, $x(\cdot) \in X_p(t_0, X_0, \mu_0)$ and $t \in [t_0, \theta]$ where

$$\rho_* = \max\{\|x\|: x \in X_0\}, \qquad r_* = cr_0(1+\mu_0), \quad r_0 = \max\{\theta - t_0, 1\}, \tag{4.2}$$

c > 0 is defined by condition (4.C).

The proof of the proposition follows from conditions (4.A)–(4.C) and Gronwall inequality. Denote

$$D = \{(t, x) \in [t_0, \theta] \times \mathbb{R}^n \colon ||x|| \le (\rho_* + r_*) \exp(r_*)\}$$
(4.3)

where ρ_* and r_* are defined by (4.2).

According to Proposition 4.1 we get that $(t, x(t)) \in D$ for every $p \in (1, +\infty)$, $x(\cdot) \in X_p(t_0, X_0, \mu_0)$ and $t \in [t_0, \theta]$. Therefore, here and henceforth we will have in mind the cylinder (4.3) as the set *D* in condition (4.B).

Note that the continuity property of the set-valued map $p \to B_p(\mu_0)$, $p \in (1, +\infty)$, implies the uniform continuity (with respect to t) of the set-valued map $p \to X_p(t; t_0, X_0, \mu_0)$, $p \in (1, +\infty)$.

Theorem 4.2. Let $p_* > 1$, $\varepsilon \in (0, \alpha_0)$ where $\alpha_0 > 0$ is defined by (2.1). Then there exists $\xi = \xi(\varepsilon) > 0$ such that the inequality

 $h_c(X_p(t_0, X_0, \mu_0), X_{p_*}(t_0, X_0, \mu_0)) \leq \varepsilon$

holds for any $p \in (p_* - \xi, p_* + \xi)$ and consequently for all $t \in [t_0, \theta]$

$$h(X_p(t; t_0, X_0, \mu_0), X_{p_*}(t; t_0, X_0, \mu_0)) \leq \varepsilon.$$

Here $h_c(S, G)$ denotes the Hausdorff distance between the sets $S \subset C([t_0, \theta]; \mathbb{R}^n)$ and $G \subset C([t_0, \theta]; \mathbb{R}^n)$ and is defined as

$$h_c(S,G) = \max\left\{\sup_{x(\cdot)\in S} d_c(x(\cdot),G), \sup_{y(\cdot)\in G} d_c(y(\cdot),S)\right\}$$

where $d_c(x(\cdot), G) = \inf\{\|x(\cdot) - y(\cdot)\|_c: y(\cdot) \in G\}, \|z(\cdot)\|_c = \max\{\|z(t)\|: t \in [t_0, \theta]\}, C([t_0, \theta]; R^n)$ is the space of continuous functions $x(\cdot): [t_0, \theta] \to R^n$.

Proof. Let

$$a_0 = L_1 r_0 + L_2 r_0 \mu_0, \qquad b_0 = L_3 \exp(a_0)$$
(4.4)

where r_0 is defined by (4.2).

By virtue of Proposition 3.6 for $\frac{\varepsilon}{b_0}$ there exists $\xi = \xi(\varepsilon)$ such that the inequality

$$h_1(B_p(\mu_0), B_{p_*}(\mu_0)) \leqslant \frac{\varepsilon}{b_0}$$

$$\tag{4.5}$$

holds for all $p \in (p_* - \xi(\varepsilon), p_* + \xi(\varepsilon))$.

Let us choose an arbitrary $p \in (p_* - \xi(\varepsilon), p_* + \xi(\varepsilon))$ and $x(\cdot) \in X_p(t_0, X_0, \mu_0)$. Then there exist $x_0 \in X_0$ and $u(\cdot) \in B_p(\mu_0)$ such that the equality

$$x(t) = x_0 + \int_{t_0}^t f(\tau, x(\tau), u(\tau)) d\tau$$
(4.6)

holds for every $t \in [t_0, \theta]$.

According to (4.5) there exists $u_*(\cdot) \in B_{p_*}(\mu_0)$ such that

$$\left\| u(\cdot) - u_*(\cdot) \right\|_1 \leqslant \frac{\varepsilon}{b_0}.$$
(4.7)

Let

$$x_{*}(t) = x_{0} + \int_{t_{0}}^{t} f(\tau, x_{*}(\tau), u_{*}(\tau)) d\tau$$
(4.8)

where $t \in [t_0, \theta]$. Then $x_*(\cdot) \in X_{p_*}(t_0, X_0, \mu_0)$. It follows from (4.B), (4.6)–(4.8) that

$$\|x(t) - x_*(t)\| \le L_3 \frac{\varepsilon}{b_0} + \int_{t_0}^t \left(L_1 + L_2 \|u_*(\tau)\|\right) \|x(\tau) - x_*(\tau)\| d\tau$$
(4.9)

for all $t \in [t_0, \theta]$. From (4.4), (4.9) and Gronwall's inequality we obtain that the inequality

$$\|x(t) - x_*(t)\| \leq \frac{\varepsilon}{b_0} L_3 \exp\left[\int_{t_0}^{\theta} \left(L_1 + L_2 \|u_*(\tau)\|\right) d\tau\right]$$
$$= \frac{\varepsilon}{b_0} L_3 \exp(a_0) = \varepsilon$$
(4.10)

holds for every $t \in [t_0, \theta]$. Since $p \in (p_* - \xi(\varepsilon), p_* + \xi(\varepsilon))$ and $x(\cdot) \in X_p(t_0, X_0, \mu_0)$ are arbitrarily chosen, we get from (4.10) that

$$X_p(t_0, X_0, \mu_0) \subset X_{p_*}(t_0, X_0, \mu_0) + \varepsilon B_c$$
(4.11)

holds for every $p \in (p_* - \xi(\varepsilon), p_* + \xi(\varepsilon))$ where B_c is unique ball of the space $C([t_0, \theta]; \mathbb{R}^n)$. Analogously, it is possible to prove that

$$X_{p_*}(t_0, X_0, \mu_0) \subset X_p(t_0, X_0, \mu_0) + \varepsilon B_c$$
(4.12)

for every $p \in (p_* - \xi(\varepsilon), p_* + \xi(\varepsilon))$.

Thus, inclusions (4.11) and (4.12) imply the validity of the theorem. \Box

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